ADVIK	P1	TPM CIRCLE NO :- 3		ACTIVITY	KK	QM	PM	JH	SHE	ОТ	DM	E&T		
		TPM CIRCLE NAME:		LOSS NO. / STEP									] KAI/FN	IDEA SHEET
		DEPT :- Q.A		RESULT AREA	Р	Q	DEF :-	Α	С	D	S	М		
CELL :- A294 S	CEL	L NAME:- Sector	MAC	HINE / STAGE :- Drillin	ng					OPI	OPERATION :- Drilling			
Dia. 4.0 Hole shift. (Drill symmetry			IDEA :- Poka yoke to be implemented as Pneumatic clamping to be provided  1) Beautiful BENCHMARK 25 No.											
found 0.8 mm shift )			countermeasure:-1) Pneumatic						1	TARGET			0 No.	
WIDELY/DEEPLY:-			cla	clamping to be provided .				rided . KAIZEN START 25.12.2014				25.12.2014		
			1	1 0 1						1	<b>TARGE</b>	T DA	TE	5.3.2015/25.5.2015
<b>PROBLEM / PRESENT STATUS -</b> A294 sector									K	KAIZEN FINISH				
Dia. 4.0 Hole shift.( Drill symmetry									П	TEAM MEMBERS :-				
found 0.8 mm shift )									Ganesh Padwalkar ,Vijay Walunj,					
										Ajit Devkar,Umesh Pimple				



Manual clamping

**BEFORE** 

Pneumatic clamping to be provided

## **RESULT:-**

Currently fixed operator & awareness given to operator

WHAT TO DO- Point to be added in Sustenance check sheet. **HOW TO DO: Audit** 

**KAIZEN SUSTENANCE** 

1. Prevent Re-occurrence Defect.

**FREQUENCY**: Alternate Day

**BENEFITS:-**

**AFTER** 

2. Reduce COPQ.

# **WHY - WHY ANALYSIS :-**

Why 1 - A294 sector Dia. 4.0 Hole shift.

Why 2 -During operation part get vibrate & disturb from his home position.

Why 3 - Clamping in complete.

Why 4 - No Poka.

**ROOT CAUSE-** –Poka

**REGISTRATION NO. & DATE:- 25.12.2014** 

**REGISTERED BY:- Ganesh Padwalkar** 

**MANAGER'S SIGN :- Sunil kinkar** 

### **COST INCURRED FOR MAKING KAIZEN**

MATERIAL COST	LABOUR COST	TOTAL COST
IN RS	IN RS	IN RS

#### SCOPE & PLAN FOR HORIZONTAL DEPLOYMENT

SR. NO.	CELL	TARGET	RESPONSIBILITY	STATUS
	A361 Lever	04.06.15	Mr.Ajeet Deokar	In-process